# Operating instructions Part B main screen overview 

Language: English

\$LastChangedRevision: 26995 \$
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## Start screen



DigiTouch Bio welcomes you. Select the word "START" to access the main menu.

## Main menu



This is the main menu.
By pressing the "Home" symbol you can return here at any time.
If the letter "R" appears next to the alarm symbol, you can reset the FC. With the letter "Ü" you can return to the overview page, with "Q" you will enter Feeding.

## Menu control



## Manual operation



## Menu materials used



## Materials used

This menu offers the same functions as the radio remote control. It provides a way of replacing this should, for example, the batteries fail.
Button REST: From the target quantity from the page products the filled quantity is subdracted.
Button GES: Here is only shown the gross weight on the large display Button FÜLL: Here is shown the filled quantity.
ATTENTION: If GES is selcted, the two line display has one line because the weight is displayed big.

## Roof



## Menu status

The status menu is described from page 8 onwards in this manual.

## Operating mode selection

Main menu -->


PART A of the manual has a more detailed description of the selection of the operation start. The selected operation start is indicated with a triangle. There are circumstances where the pressing of a button does not necessarily lead to a mode being changed, since for example, the return must be carried out first.

## Page alarms

Main menu --> Alarms

| Alarms D |  | IgiToucht |
| :---: | :---: | :---: |
| 11:01:25 | Load cell 1 no response | 21-12-2021 |
| 11:01:25 | Fault hydraulic roof power unit | 21-12-2021 |
| 11:01:25 | ault roof L2 hydraulic power uni | 21-12-2021 |
| 11:01:25 | Fault L2 hydraulic power unit | 21-12-2021 |
| 11:01:25 | ault right elevated screw convey | 21-12-2021 |
| 11:01:25 | ault right lateral screw conveyo | 21-12-2021 |
| 11:01:25 | Fault right mixer | 21-12-2021 |
| 11:01:25 | Faut right feed | 21-12-2021 |
|  | H |  |

The pending alarms are shown here. Alarms, which are not in the queue, disappear from this list immediately. The alarms need not be confirmed or acknowledged. Particular executions of the frequency converters are an exception.
With button " H " a history of past alarms can be shown.

## Alarm history page



Past alarms are shown here.
In the menu "free memory" (see page 27) can the history be deleted.

## Feed

Main menu --> Q


## Menu settings

Main menu --> Settings


In this menu the equipment can be configured.
A separate description of each individual point can be found below.

## Configure parameter/s

See pages 24 to 26

## Timer

Main menu -->


Timer
Here you can edit the integrated timer settings. You can enable or disable them below.
ATTENTION: When there is an external control present, this would normally take over the function of the timer. This should then be set to inactive here.

## Edit product

Main menu -->

## DigiTouch $\boldsymbol{j}$

| Short |  | Product | Target amount |  |
| :---: | :---: | :---: | :---: | :---: |
| 0 | NULL | Null | 3000 | $\Delta$ |
| 1 | MAIS | Mais | 3000 |  |
| 2 | GRAS | Gras | 3000 |  |
| 3 | MIST | Mist | 3000 |  |
| 4 | GETR | Getreide | 3000 |  |

## Product

This menu allows you to enter both the name of the product and the target amount. The names are processed in any case, but they only are displayed at the 1. of every month in the input material diary. The quantities are used only if the operating moder "REST" on the page input material or the remote control is selected.

## Menu miscellaneous

Main menu -->
Settings -->
DigiToucht
Miscellaneous

Diagnosis
Default values
Operator
USB
Weighing history

## Miscellaneous

Additional menu items, which are only selected occasionally.
See pages 27 to 36

## Menu default settings

| Main menu --> | Settings --> |
| :--- | :---: |
| Basic settings | DigiTouchit |

Basic settings Very basic settings can be configured in this menu. System type and equipment are for users not available.

## Menu status

The status menu is described from page 8 onwards in this manual.

## Type 0

## DigiTouch Scale only

## Status display <br> Main menu --> Status

| Status |  | DigiTouch $\hat{j}$ |
| :---: | :---: | :---: |
| Manual |  |  |

The current stage is displayed at the top and the active motors (rotating white circles) directly in the middle of this screen. $R / L$ shows which feeding container and/or the direction of rotation of the respective screw
(right or left) of the respective fermenter. Only relevent for double systems.
Below there are 5 symbols representing the different status indicators.
See pages 22 and 23
In addition, the limit switches are visualized.

## Manual operation

Main menu --> Control -->
Manual operation DigiTouchis
This screen provides
no function. Except for other system types. See page 8 till 21.
Type 0 has no manual operation

## Type 10

## Rondomat <br> lower feed

## Status display



The current stage is displayed at the top and the active motors (rotating white circles) directly in the middle of this screen.
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Below there are 5 symbols representing the different status indicators.
See pages 22 and 23
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## Manual operation



This screen facilitates manual operation of the individual drives. Normally this is not necessary. Type 0 has no manual operation. Before switch on the direction of rotation L/R (left/right fermenter) has to be selected, than the screw conveyor go`s left or right. This depends on the construction of the system and is shown in the system plan.
WARNING: No monitoring in this case.
Screen can only be used when manual operation has been selected.

## Type 11

## Rondomat upper feed

## Status display



The current stage is displayed at the top and the active motors (rotating white circles) directly in the middle of this screen.
R/L shows which feeding container and/or the direction of rotation of the respective screw (right or left) of the respective fermenter. Only relevent for double systems.
Below there are 5 symbols representing the different status indicators.
See pages 22 and 23
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## Manual operation



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WARNING: No monitoring in this case. Screen can only be used when manual operation has been selected.

## Type 12

## Rondomat upper rear feed

## Status display



The current stage is displayed at the top and the active motors (rotating white circles) directly in the middle of this screen.
$R / L$ shows which feeding container and/or the direction of rotation of the respective screw (right or left) of the respective fermenter. Only relevent for double systems.
Below there are 5 symbols representing the different status indicators.
See pages 22 and 23
In addition, the limit switches are visualized.

## Manual operation



This screen facilitates manual operation of the individual drives. Normally this is not necessary. Type 0 has no manual operation. Before switch on the direction of rotation L/R (left/right fermenter) has to be selected, than the screw conveyor go`s left or right. This depends on the construction of the system and is shown in the system plan.
WARNING: No monitoring in this case. Screen can only be used when manual operation has been selected.

## Type 13

## Rondomat upper rear feed

## Status display



The current stage is displayed at the top and the active motors (rotating white circles) directly in the middle of this screen. $R / L$ shows which feeding container and/or the direction of rotation of the respective screw (right or left) of the respective fermenter. Only relevent for double systems.
Below there are 5 symbols representing the different status indicators.
See pages 22 and 23
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## Manual operation



This screen facilitates manual operation of the individual drives. Normally this is not necessary. Type 0 has no manual operation. Before switch on the direction of rotation L/R (left/right fermenter) has to be selected, than the screw conveyor go`s left or right. This depends on the construction of the system and is shown in the system plan.
WARNING: No monitoring in this case. Screen can only be used when manual operation has been selected.

## Type 20

## extension Rondomat lower feed

## Status display



The current stage is displayed at the top and the active motors (rotating white circles) directly in the middle of this screen. $R / L$ shows which feeding container and/or the direction of rotation of the respective screw (right or left) of the respective fermenter. Only relevent for double systems.
Below there are 5 symbols representing the different status indicators.
See pages 22 and 23
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## Manual operation



This screen facilitates manual operation of the individual drives. Normally this is not necessary. Type 0 has no manual operation. Before switch on the direction of rotation L/R (left/right fermenter) has to be selected, than the screw conveyor go`s left or right. This depends on the construction of the system and is shown in the system plan.
WARNING: No monitoring in this case. Screen can only be used when manual operation has been selected.

## Type 21

## extension Rondomat upper feed

## Status display



The current stage is displayed at the top and the active motors (rotating white circles) directly in the middle of this screen. R/L shows which feeding container and/or the direction of rotation of the respective screw (right or left) of the respective fermenter. Only relevent for double systems.
Below there are 5 symbols representing the different status indicators.
See pages 22 and 23
In addition, the limit switches are visualized.

## Manual operation



This screen facilitates manual operation of the individual drives. Normally this is not necessary. Type 0 has no manual operation. Before switch on the direction of rotation L/R (left/right fermenter) has to be selected, than the screw conveyor go`s left or right. This depends on the construction of the system and is shown in the system plan.
WARNING: No monitoring in this case. Screen can only be used when manual operation has been selected.

## Type 22

## extension Rondomat upper rear feed

## Status display



The current stage is displayed at the top and the active motors (rotating white circles) directly in the middle of this screen. R/L shows which feeding container and/or the direction of rotation of the respective screw (right or left) of the respective fermenter. Only relevent for double systems.
Below there are 5 symbols representing the different status indicators.
See pages 22 and 23
In addition, the limit switches are visualized.

## Manual operation



This screen facilitates manual operation of the individual drives. Normally this is not necessary. Type 0 has no manual operation. Before switch on the direction of rotation L/R (left/right fermenter) has to be selected, than the screw conveyor go`s left or right. This depends on the construction of the system and is shown in the system plan.
WARNING: No monitoring in this case. Screen can only be used when manual operation has been selected.

## Type 23

## extension Rondomat upper rear feed

## Status display



The current stage is displayed at the top and the active motors (rotating white circles) directly in the middle of this screen. $R / L$ shows which feeding container and/or the direction of rotation of the respective screw (right or left) of the respective fermenter. Only relevent for double systems.
Below there are 5 symbols representing the different status indicators.
See pages 22 and 23
In addition, the limit switches are visualized.

## Manual operation

This screen facilitates manual operation of the individual drives. Normally this is not necessary. Type 0 has no manual operation. Before switch on the direction of rotation L/R (left/right fermenter) has to be selected, than the screw conveyor go`s left or right. This depends on the construction of the system and is shown in the system plan.
WARNING: No monitoring in this case. Screen can only be used when manual operation has been selected.

## Type 30

## Duplex lower feed

## Status display



The current stage is displayed at the top and the active motors (rotating white circles) directly in the middle of this screen.
R/L shows which feeding container and/or the direction of rotation of the respective screw
(right or left) of the respective fermenter. Only relevent for double systems.
Below there are 5 symbols representing the different status indicators.
See pages 22 and 23
In addition, the limit switches are visualized.

## Manual operation



This screen facilitates manual operation of the individual drives. Normally this is not necessary. Type 0 has no manual operation. Before switch on the direction of rotation L/R (left/right fermenter) has to be selected, than the screw conveyor go`s left or right. This depends on the construction of the system and is shown in the system plan.
WARNING: No monitoring in this case. Screen can only be used when manual operation has been selected.

## Type 32

## Duplex upper feed

## Status display



The current stage is displayed at the top and the active motors (rotating white circles) directly in the middle of this screen.
R/L shows which feeding container and/or the direction of rotation of the respective screw
(right or left) of the respective fermenter. Only relevent for double systems.
Below there are 5 symbols representing the different status indicators.
See pages 22 and 23
In addition, the limit switches are visualized.

## Manual operation



This screen facilitates manual operation of the individual drives. Normally this is not necessary.
Type 0 has no manual operation. Before switch on the direction of rotation L/R (left/right fermenter) has to be selected, than the screw conveyor go`s left or right. This depends on the construction of the system and is shown in the system plan.
WARNING: No monitoring in this case. Screen can only be used when manual operation has been selected.

## Type 40

## Double Rondomat

 lower feed
## Status display



The current stage is displayed at the top and the active motors (rotating white circles) directly in the middle of this screen. $\mathrm{R} / \mathrm{L}$ shows which feeding container and/or the direction of rotation of the respective screw (right or left) of the respective fermenter. Only relevent for double systems.
Below there are 5 symbols representing the different status indicators.
See pages 22 and 23
In addition, the limit switches are visualized.

## Manual operation



This screen facilitates manual operation of the individual drives. Normally this is not necessary. Type 0 has no manual operation. Before switch on the direction of rotation L/R (left/right fermenter) has to be selected, than the screw conveyor go`s left or right. This depends on the construction of the system and is shown in the system plan.
WARNING: No monitoring in this case. Screen can only be used when manual operation has been selected.

## Type 50

## Double Rondomat as Duplex lower feed

## Status display



The current stage is displayed at the top and the active motors (rotating white circles) directly in the middle of this screen.
$R / L$ shows which feeding container and/or the direction of rotation of the respective screw (right or left) of the respective fermenter. Only relevent for double systems.
Below there are 5 symbols representing the different status indicators.
See pages 22 and 23

## Manual operation

In addition, the limit switches are visualized.


This screen facilitates manual operation of the individual drives. Normally this is not necessary. Type 0 has no manual operation. Before switch on the direction of rotation L/R (left/right fermenter) has to be selected, than the screw conveyor go`s left or right. This depends on the construction of the system and is shown in the system plan.
WARNING: No monitoring in this case. Screen can only be used when manual operation has been selected.

## Type 51 / 52

## Double Rondomat as Duplex upper feed

## Status display 51



Status display 52


The current stage is displayed at the top and the active motors (rotating white circles) directly in the middle of this screen. $R / L$ shows which feeding container and/or the direction of rotation of the respective screw (right or left) of the respective fermenter. Only relevent for double systems.
Below there are 5 symbols representing the different status indicators.
See pages 22 and 23
In addition, the limit switches are visualized.

## Manual operation <br> See pages 20

## Symbol "kg" (portion)



Here the portion is adjusted. (black box portion target).
With ++ and -- the portion can be increased or reduced/left out for the next feeding.
Portion "is" = to reach the target weight with the feeding quantity
Portion "target" = adjustet dosing quantity
Feed "is" = quantity of the last feeding
Feed "target" = quantity, that should be reached with the next feeding
Weight "is" = gross weight less feeding quantity
Weight "target" = gross weight after the next feeding.
With this new procedure the containers will be empty "on the dot".
ATTENTION: The portion can only be adjusted in filling mode and operating mode "Off"!

## Symbol "s" (timer)



## Times "E"



## Symbol "A" (power display)



## SyMnooriviv (tera)



The power indicator remains blank when in idle mode. A value indicating power as well as the limit value is only displayed when a particular motor is running. If a limit value is exceeded, the conveyer from the previous stage is stopped in order to reduce material supply. As a result, blockages and overloads are reduced and prevented!
See pages 25 to 26

The special times are displayed here. Variable depending on the equipment of the system.

## Configure parameter/s

Setting the operating parameters
With a higher-level control such as Profibus, Profinet etc. have to set the times like this be because it is the given time from the higher-level control for a dosing cycle do not exceed.

## Times 1

Main menu --> Settings --> Parameter


Pre- and afterrun times.
ATTENTION: The menu conforms to the equipment configuration. Here the lead time or Follow-up time of each Conveyor screws set.

## Times 2

Main menu -->
Settings -->

| Times 2 |  | DigiTo <br> Afterrun (rıın dnwn) <br> 0s |
| :---: | :---: | :---: |
|  | $\begin{gathered} \text { Prerun } \\ \text { (ctartıın) } \\ \hline \end{gathered}$ |  |
| Metering screw1 | Os |  |
| Metering screw2 | Os | Os |
| Metering screw3 | Os | Os |
| Metering screw4 | Os | Os |
| Metering screw5 | Os | Os |
| Metering screw6 | Os | Os |

## Times 3

Main menu -->


Parameter --> 2x
Cycle time of the sliding floor. Must be adapted to the material. Maximum dosing time --> Switch- off due to exceedance.
Emptying stroke - when the end position is reached the wall retracts repeatedly in order to reduce the residue quantities.

## Times 4

Main menu -->
Settings -->

| Times 4 | DigiTouchi |
| :---: | :---: |
| DUMP-Signal | 1.7 s |
| Waage Beruhigen | 1.7 s |
| Mixer slow EXTRA | 0 s |
| Mixer fast EXTRA | 0 s |
|  |  |
|  |  |
|  |  |

## Current limit 1

Main menu --> Settings -->


## Current limit 2

Main menu --> Settings -->
Rondomat


Parameter --> $5 \times \boxtimes$

## Multimix



Only if "Push ram MAX" gets undershot by the extension Rondomat/Micromix and the mixer in the big rotational speed is then the Sliding floor pushes.
If "small" "A" gets undershot the mixer switches to the big rotational speed.
If "big" "A" gets overshot the mixer switches to the small rotational speed.
Set current depending on the module

## Miscellaneous

Main menu --> Settings -->


Parameter --> 6x $\triangle$
Max. return: Maximum time for the valve return.
Retraction: When Filling is switched to Automatic the Wall moves $X$ seconds forward (precompression).
Minimum weight, below which the equipment switches off.
The system unlocks with double minimum weight.
Screw conveyors only appear if the conveyor screws in the equipment selected with FU. Here it is possible to adjust the fixed speed of the individual screws.

## Diagnosis



## Information



Miscellaneous --> Diagnosis
Here are displayed the information of SPS itself.
At SerialPortCOM1Use has to be "User Only"
This page should be checked Monthly if battery shows "OK". If it is not "OK" the battery has to be replaced according to biogas control manual part C: DC1000. For EC1000 no battery replacement is possible.

## Free space

| Main menu --> <br> Free space | Settings --> |
| :--- | :--- |
| Free space | DigiTouchit |



Miscellaneous --> Diagnosis -->
Amount of free memory.
Button to delete the alarm history and to free memory. Internal Memory = left column The external memory (right column) can only be used if there is a SD-card integrated and activated.

## Project info

Main menu -->
Settings -->
Miscellaneous --> Diagnosis -->
Project info

| Project info: |  | DigiToucht |
| :---: | :---: | :---: |
| Project: | Biogas_PrintoutManual.pro |  |
| Project date: | DT\#2021-12-15-10:02:48 |  |
| Project title: | J-03-24 10:38:38Z hoepffr \$ |  |
| Project author: | \$LastChangedBy: hoepffr \$ |  |
| Project descripti | Norkspacelnformation.pin \$ |  |
| Version: | tChangedRevision: 25980 \$ |  |
| Project ID: | 556025 |  |
| Retain size: | 2396 |  |

## Bus Diagnosis

Main menu --> Settings -->
Bus Diagnosis


Project information, such as type, Program Version date etc.. This information are very important for an update, also for the replacement of the SPS or of the touch panels.

## CAN bus load <br> Main menu --> Settings --> Miscellaneous --> Diagnosis -->

CAN Diagnostics


$$
\begin{gathered}
\text { Bus load: } \\
0.2 \%
\end{gathered}
$$

Bus load on the CAN bus.
If the bus load shows over $40 \%$ for a longer period, then at least one participant has constant errors.

# CAN Diagnostics 

| Main menu --> | Settings --> | Miscellaneous --> | Diagnosis --> |
| :--- | :---: | :---: | :---: |
| Bus Diagnosis --> | CAN Diagnostics 2 |  |  |


| CAN Diagnostics DigiToucht |  |  | The different CAN devices top down: |
| :---: | :---: | :---: | :---: |
| Node: Bus status: |  |  | master. |
| 32 |  |  | The boxes at the bottom are the |
| 32 | 97 |  | slaves and their status. |
| 33 | 97 97 |  | Node 32: Can 32 module (Phoenix-Len |
| $\begin{array}{r}34 \\ 35 \\ \hline\end{array}$ | 97 |  | Node 33: Mixer FU |
| 36 | 97 |  | Node 34: Screw 1 |
| $\begin{array}{r}37 \\ 38 \\ \hline\end{array}$ | 97 97 | - Node 35: Screw 2 |  |
| 39 | 97 |  | Node 36: Screw 3 |
| 40 | 97 |  | Node 37: Screw 4 |
| Node 38: 2. Lenze module CAN master analog output FU1.. FU4 The status in detail: |  |  |  |
|  |  |  |  |
|  |  |  |  |

## MASTER:

Status $0,1,2$ : They run from the master automatically and in the first cycles following an SPS start.
Status 3: Status 3 of the master will be retained for some time.
Status 5: Status 5 is the normal operating mode for the master.
SLAVE:
Status -1: The slave is reset by the NMT message [reset node] and changes independently into status 1.
Status 1: The slave changes after a maximum time of 2 seconds, or immediately after receiving its boot-up message into status 2.
Status 2: The slave automatically changes into status 3 after a delay of 0.5 seconds.
This time confirms that many open CAN devices are not immediately ready to receive their configuration SDOs, after they have sent their boot-up messages.
Status 3: In status 3 the slave is configured. Slaves where a problem arises during the configuration phase, stay in status 3 or change directly into a failure state following the configuration phase (status $>5$ ).
Status 5: Status 5 is the slaves normal operating mode.
Status 97: A node changes into status 97 when it is operational (Operational device in the CAN configuration) and not on the SDO request, after the object has responded with $0 \times 1000$.
Status 98: A node changes to Status 98, when the device type (object 0x1000) does not correspond to the configuration type.

## Modbus RTU

Main menu --> Settings --> Miscellaneous --> Diagnosis -->
Bus Diagnosis --> Modbus RTU


## ADAM module

| Main menu --> | Settings --> | Miscellaneous --> |
| :--- | :---: | :---: |
| Bus Diagnosis --> | Modbus RTU --> | Diagnosis --> |



## ADAM module 1

Main menu --> Settings -->
Bus Diagnosis --> Modbus RTU -->


## PROFIBUS DC1005

Main menu --> $\quad$ Settings -->
Bus Diagnosis --> PROFIBUS $\quad$ Miscellaneous --> Diagnosis -->

| PROFIBUS |  | DigiTouchit |  |
| :--- | :---: | :---: | :---: |
| Baudrate | 500 | ++ | -- |
| Node-ID | 25 |  |  |
| Max. Node-ID | 25 |  |  |
| in Config |  |  |  |
| Available <br> Error |  |  |  |

Baud rate: Setting is defined by the master, can be adjusted with ++ and -- for master to slave communication
Node-ID: Address of the feeding container is indicated by the customer.
Max. Node-ID: Highest Node-ID of the profibus network.
Nodes with Errors: Amount of the incorrect subscribers
in Config = activated
Availiable $=$ connected

## PROFIBUS_EC1000


Main menu --> Settings --> Miscellaneous --> Diagnosis -->

Bus Diagnosis --> PROFINET

| PROFINET | Digitowchis |
| :--- | :---: |
| Version V 0.0 .0 | CPU |
| States |  |
| Connection State | $29 \%$ |
| Provider State Controller |  |
| Consumer State Controller |  |
| Provider State Device |  |
| Consumer State Device |  |

When it says version V0.0.0 Profinet is not available for this system or it is not installed.
The CPU usage should not be over $60 \%$ for a longer period. If this is the case the transmission speed of the busses have to be slow down. This can be done with the higher-level control. For example for Siemens S7 the update time has to be 8000 ms by the IO-cycle. The accepted update cycles have to be without IO-dates 15 and the watchdog time 120000 ms .
Connection State, Provider State Controller and Consumer State Controller shows if there is a connection. Provider State Device and Consumer State Device shows if Profinet is active.
DC_ProfinetDevice V1.1.0 has to be noted for commissioning.

## ETHERCat

Main menu --> Settings --> Miscellaneous --> Diagnosis -->

Bus Diagnosis --> ETHERCat

Bus Diagnosis DigiTouchi | Only EC1000 has this page |
| :--- |
| DeviceScan is the bus scan which |
| can be performed with the EasiCat. |
| Ecmaster is the EC1000 itself(SPS2) |
| XR01 is the first expansion |
| card (SPS3) |
| XR02 is the second expansion |
| card (SPS4) |

Main menu --> Settings --> Miscellaneous --> Diagnosis -->
Bus Diagnosis --> ETHERCat DeviceScan

## EtherCAT Device List

|  | konfigurierte Devices |  |  | gefundene Devices |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Vendor-1D | Product-ID | Revision-No | Vendor-ID | Product-ID | Revision-No | Status |  |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | $\star$ |
| 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |  |
| 2 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |  |
| 3 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |  |
| 4 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |  |
| 5 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |  |
| 6 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |  |
| 7 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |  |
| 8 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |  |
| 9 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |  |
| 10 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |  |
| 11 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |  |
| 12 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |  |
| 13 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |  |
| 14 | 0 | 0 | 1280 | 0 | 0 | 0 | 0 |  |
| 15 | 0 | 0 | 65734144 | 0 | 0 | 0 | 0 |  |
| 16 | 0 | 0 | 2123776 | 0 | 0 | 0 | 0 |  |
| 17 | 0 | 0 | 16803840 | 0 | 0 | 0 | 0 |  |
| 18 | 0 | 0 | 458768 | 0 | 0 | 0 | 0 |  |
| 19 | 0 | 0 | 65792 | 0 | 0 | 0 | 0 |  |
| 20 | 0 | 0 | 26624 | 0 | 0 | 0 | 0 |  |
| 21 | 0 | 0 | 16780544 | 0 | 0 | 0 | 0 |  |
| 22 | 0 | 0 | 458770 | 0 | 0 | 0 | 0 |  |
| 24 | 0 | 0 | 131328 | 0 | 0 | 0 | 0 |  |
| 25 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |  |
| 2 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | - |

On the left side are displayed the existing subscribers of the project and on the right side are displayed the detected subscribers after the scan. The difference to the bus scan from EasiCat is, that here are only shown the IDs and not the names.

ECMaster


## XR01

Main menu --> Settings --> Miscellaneous --> Diagnosis -->

Bus Diagnosis --> ETHERCat XR01


Here the digital input and output can be diagnosed. The analog outputs are also shown. The LEDs on the XR01 are explained here: Biogas control instruction part C:
E IO XR module

Settings -->
ETHERCat

Miscellaneous --> Diagnosis -->
XR02


Here the digital input and output can be diagnosed. The analog outputs are not shown. The LEDs on the XR02 are explained here: Biogas control instruction part C: E IO XR module

## EXTERN 1

Main menu --> Settings --> Miscellaneous --> Diagnosis --> Bus Diagnosis --> EXTERN 1


DIG = digital input
PB = Profibus
PN = Profinet
MB = Modbus
!= Boolean operator is shown, if pause negate is selected in the external equipment
$\mathrm{M}=$ Flag, pause signal is extended
A filled in circle means, that it is selected
The numbers on the right side shown how often pause, On_term, On_pulse and Off_pulse were strucked
Main menu --> Settings --> Miscellaneous --> Diagnosis -->


## Set default values



Miscellaneous --> Default values
Default values: Load the last default values.
Default values new: Here the default values can be newly saved. This is only possible for service technicians

## Operator

| Main menu --> | Settings --> |
| :---: | :---: |
| Operator | DigiTouchit |


| Chassis no. | F12345 |
| :---: | :---: |
| Job no. | AU-123456 |
| Short name | Muster |
|  | PR-D12345678 |

Miscellaneous --> Operator Shown here is all the inportant information of the machine which are necessary for spare parts and service requests.

## USB

Main menu -->


Miscellaneous --> USB
This mask serves to read the feed material log books. Alternatively this data can be retrieved using an Ethernet connection. You have to press "Go" several times until the message concerning the safe removal of the USB stick is displayed. ATTENTION: In some cases the USB stick isn't recognized, e.g. if it has a wrong communication protocol. Try again with another USB stick.

## Weighing history <br> Main menu -->

Settings -->
Weighing history

# Weighing history DigiTouch $\hat{\beta}$ 

No.
Nr Zeit 及ollkgistkgbaue $\boldsymbol{\wedge}$

## Miscellaneous -->

Here actual and target quantities, feeding time and duration are recorded. If a software update performed the history scale is deleted. How to reset the history scale is explained in the biogas control manual part C .

## Setup menu



The menus (system type) shown here are for the setup mode and not intended for the user. They are protected with a code. Here the respective system type that is fitting to the machine can be selected. Is different depending on project status.



Main menu --> Basic settings -->


Equipment model
Equipment model DigiTouch


Equipment model

## Equipment model <br> 

Rondomat Vario with BAC x2


Equipment model
Equipment model DigiTouchis



## Equipment



## Equipment

The menu (equipment) displayed here are for the setup and not for the operator. They are protected with a code.
The respective screws of the machine can be selected here.
Attention: If there is a frequency converter for one screw, "No" has to be selected.
ATTENTION: If analogue output is activated for EC1000, the current measurement of the screw does not work and has to be disconnected and the screw has to be deactivated.


Equipment -->
Determine whether the screws be operated with or without FU.
If one screw is operated without FU, here the respective screw has to be set "No".


Equipment -->
Agitator "Yes": When controlling the agitator, only then a signal is outputted to an external agitator Mixer "Yes": If mixer controlled contactor.
Mixer RE is only needed if there are 2 mixers and they should run by turns (left/right mixer)
Mixer FU "Yes": If with FU
Emergency stop: An alarm is only given if "Yes" is selected, only for digitouch solo if "No"
Floor: Only with "Yes" signal on the hydraulic unit


If it is a duplex system here the respective metering screws can be activated. In a special case it is also for other system types possible to misuse 1 to 4 metering screws as so-called special contactors. The amount of the metering screws depend on the system types.

Equipment

## 4x

Here it is possible to set if the feeding container has a roof, with or without end position sensor.
Portion (++/--): With this field it is activated, that the customer has the possibility, dosing an additional portion or omit a portion during the automatic mode.


Equipment ${ }_{5 \times}$ -
The screws RE 1-3 are provided for dosing with one feeding container on 2 fermenters.
Switch off after time: activates the maximum dosing time seatable Profibus ID ?: only with Profibus connection, has to be activated here Analog output: is the $4-20 \mathrm{~mA}$ output of the scale to the customer. ATTENTION: If it is activated the current measurement of the contactor does not work for screw 4 and has to be disconnected and the screw 4 has to be deactivated and for DC1000 without black plugs has to be activated the Can module 32.


Equipment
Here the external pause signal can be negated, that means that the signals applied permanent and only decrease if the respective signal switches.

## Scale

| Main menu --> | Basic settings --> | Scale |
| :---: | :---: | :---: |
| Scale | DigiTouch | The overview menu enables access to all weighing scale setting and |
| External display | Cells | diagnosis functions. |
| Radio remote control | Active 1 |  |
| Ports | Scale detail |  |
| Miscellaneous |  |  |
| Login |  |  |

External display 1-4
Main menu --> Basic settings --> External display


Activating an external display.
ATTENTION: Many settings require a new start for them to take effect. Active: Shows how many displays are active, at maximum 1 display can be active. If accidentally more displays are activated, all displays have to be deactivated. If active 0 then the correct display should be selected. After that wait 15 seconds, press the house and after waiting again 15 seconds restart.

## External display 5-6

Main menu -->


Activating an external display. ATTENTION: Many settings require a new start for them to take effect. Active: See external display 1-4 ATTENTION: Ronan 1 -line and Fliegl 1-line should not be selected because this types hav always 2 -lines.

## Display 1 detail (1 line)



External display --> Ronan 1 line


Detailed view of the display, for all 1 line displays the mask looks like this (1 data area).

## Display 2 detail (2 lines)

Main menu -->
External display -->
Basic settings --> Scale -->



Here you can activate night mode ( T ). At the bottom of the page the time can be set, from when till when the display is activated. Or continuous mode (1) or continuous-OFF (0)

## Radio remote control

Main menu --> Basic settings --> Scale --> Radio remote control


Touch box to activate
Touch bar to get to details.
Only select 15 touch radio if no SD-card has been inserted and activated. Otherwise no Profinet is possible. Active: Shows how many radio remote controls are active.

## Radio remote control detail 15 keys

Main menu --> Basic settings -->
Radio remote control -->
Radio 15 keys


## Radio remote control detail 12 keys <br> Basic settings --> <br> Radio remote control --> Radio 8 keys

DigiTouchi


Detailed view radio. The serial number is saved here using "learn".
Sender ID: Only if the address of the radio is displayed, "learn" can be used.
Number field shows which signals come from the radio.

## COM ports

Main menu --> Basic settings -->
Ports


## Cells 1-4

Main menu -->
Basic settings -->
Display of the 3 COM port baud rates.
For diagnostic purposes!
COM1 = Display (display variations)
COM2 = Radio 15 buttons
COM3 = Scale, radio 12 buttons, adam mode

Cells


Overview of 4 cells each.
Arrows for browsing. Touch box to activate Touch bar to get details. If done counts, all right. If timeout counts up, cell faulty. "Active": Shows how many cells are active per page

Cell 1
Main menu --> Cells -->


$\begin{array}{lrr}\text { Main menu --> } & \text { Basic settings }--> \\ \text { Cells --> } & \text { Cell } 1 \text {--> } & \text { Enable }->\text { K }\end{array}$


Detail menu including
setting minimum and maximum cell loading;
Filter A (and C in older versions)
Programming the weight cell with "K"
If error counts up, cell is defective Division $10 \mathrm{~kg}=$ cell D50 Division $1 \mathrm{~kg}=$ all other D-types

## Miscellaneous

Main menu -->
Basic settings -->
Scale -->
Miscellaneous


Weigh Cell Timeout: response time of the cell Error Free Time Weighing: time when consectuive errors not lead to the cancellation of the feeding Show Errors: Deactivate/Activate, that alarms be displayed ATTENTION if "No" it can come to uncontrolled dosing -> complete dosing all at once)
Call Each x Cycle: Selection if every x-cycle from the scale is accessed

## Login

Main menu -->
Basic settings -->

## Scale -->

Login


## Analogue output $4 . .20 \mathrm{~mA}$



Analogue output
Parameterisation of the analogue output. Simulation can be used, in order to make a comparison with the higher-level control system.
The red boxes with mA values shown the scaling of the system.
With the black boxes with the kg values the settings of the filling weight can be made. This has to accord to the higher-level system.
The mA value besides the black boxes shows the current output mA value

## Language selection

## Language

Here you can specify if working locally or at a remote location. "Working locally" relate to DC1000 panel and the VNC mode of EC1000 "Remote location" relate to Web-Visu, the Java visualisation, which can be reached from for example http://10.20.10.2:8040/webvisu.htm It also relate to the http visualisation of the external touch panel, the digitouch and the spidercontrol app.

# Local language selection 

Main menu -->
Basic settings --> On panel

$\underset{\text { Main menu }-\gg}{\text { Language }} \underset{\text { Basic settings --> }}{\text { selection }}$
remote


# Language file information 

## Main menu --> Basic settings --> <br> Language <br> DigiToucht

Language --> i
The language file version

Meldungen.xml:tChangedRevision: 25425 \$
modi.xml: tChangedRevision: 19152 \$
sprachen.xml:tChangedRevision: 19152 \$
alarmmeld.xml:tChangedRevision: 25425 \$
allgemein.xml: tChangedRevision: 27049 \$
weiteres.xml: tChangedRevision: 27043 \$
weiteres2.xml:tChangedRevision: 27049 \$

## Alarm texts

| 0 | system/alarmgroupallalarms 0 | 8 | Fault right feed |
| :---: | :---: | :---: | :---: |
| 1 | Emergency stop | 9 | Fault hydraulic roof power unit |
| 2 | Fault screw 2 | 10 | Fault valve fuse |
| 3 | Fault screw 3 | 11 | Fault roof L2 hydraulic power uni |
| 4 | Fault screw 1 | 12 | Fault L2 hydraulic power unit |
| 5 | Fault roof valve fuse | 13 | Fault L2 valve fuse |
| 6 | ult variable frequency mixer mot | 14 | ault right elevated screw convey |
| 7 | Fault hydraulic power unit | 15 | Fault right lateral screw conveyol |


| 16 | Fault screw 4 | 24 | Fault right mixer |
| :---: | :---: | :---: | :---: |
| 17 | Fault metering screw1 | 25 | A1 card error |
| 18 | Fault metering screw 2 | 26 | Fault FC screw 4 |
| 19 | Fault metering screw 3 | 27 | A2 card error |
| 20 | Fault metering screw 4 | 28 | A3 card error |
| 21 | Fault metering screw 5 | 29 | Fault FC screw 3 |
| 22 | Fault metering screw 6 | 30 | Fault FC screw 2 |
| 23 | Fault mixer | 31 | Fault FC screw 1 |


| 32 | Load cell 1 error | 40 | Load cell 9 error |
| :---: | :---: | :---: | :---: |
| 33 | Load cell 2 error | 41 | Load cell 10 error |
| 34 | Load cell 3 error | 42 | Load cell 11 error |
| 35 | Load cell 4 error | 43 | Load cell 12 error |
| 36 | Load cell 5 error | 44 | Load cell 13 error |
| 37 | Load cell 6 error | 45 | Load cell 14 error |
| 38 | Load cell 7 error | 46 | Load cell 15 error |
| 39 | Load cell 8 error | 47 | Load cell 16 error |


| 48 | Load cell 1 no response | 56 | Load cell 9 no response |
| :---: | :--- | :---: | :--- |
| 49 | Load cell 2 no response | 57 | Load cell 10 no response |
| 50 | Load cell 3 no response | 58 | Load cell 11 no response |
| 51 | Load cell 4 no response | 59 | Load cell 12 no response |
| 52 | Load cell 5 no response | 60 | Load cell 13 no response |
| 53 | Load cell 6 no response | 61 | Load cell 14 no response |
| 54 | Load cell 7 no response | 62 | Load cell 15 no response |
| 55 | Load cell 8 no response | 63 | Load cell 16 no response |


| 64 | system/alarmgroupallalarms 64 | 72 | system/alarmgroupallalarms 72 |
| :---: | :--- | :---: | :--- |
| 65 | system/alarmgroupallalarms 65 | 73 | system/alarmgroupallalarms 73 |
| 66 | system/alarmgroupallalarms 66 | 74 | system/alarmgroupallalarms 74 |
| 67 | system/alarmgroupallalarms 67 | 75 | system/alarmgroupallalarms 75 |
| 68 | system/alarmgroupallalarms 68 | 76 | system/alarmgroupallalarms 76 |
| 69 | system/alarmgroupallalarms 69 | 77 | system/alarmgroupallalarms 77 |
| 70 | system/alarmgroupallalarms 70 | 78 | system/alarmgroupallalarms 78 |
| 71 | system/alarmgroupallalarms 71 | 79 | system/alarmgroupallalarms 79 |

## Alarm texts

| 80 | system/alarmgroupallalarms 80 | 88 | system/alarmgroupallalarms 88 |
| :---: | :---: | :---: | :---: |
| 81 | system/alarmgroupallalarms 81 | 89 | system/alarmgroupallalarms 89 |
| 82 | system/alarmgroupallalarms 82 | 90 | system/alarmgroupallalarms 90 |
| 83 | system/alarmgroupallalarms 83 | 91 | system/alarmgroupallalarms 91 |
| 84 | system/alarmgroupallalarms 84 | 92 | system/alarmgroupallalarms 92 |
| 85 | system/alarmgroupallalarms 85 | 93 | system/alarmgroupallalarms 93 |
| 86 | system/alarmgroupallalarms 86 | 94 | system/alarmgroupallalarms 94 |
| 87 | system/alarmgroupallalarms 87 | 95 | system/alarmgroupallalarms 95 |


| 96 | system/alarmgroupallalarms 96 | 104 | system/alarmgroupallalarms 104 |
| :---: | :--- | :---: | :--- |
| 97 | system/alarmgroupallalarms 97 | 105 | system/alarmgroupallalarms 105 |
| 98 | system/alarmgroupallalarms 98 | 106 | system/alarmgroupallalarms 106 |
| 99 | system/alarmgroupallalarms 99 | 107 | system/alarmgroupallalarms 107 |
| 100 | system/alarmgroupallalarms 100 | 108 | system/alarmgroupallalarms 108 |
| 101 | system/alarmgroupallalarms 101 | 109 | system/alarmgroupallalarms 109 |
| 102 | system/alarmgroupallalarms 102 | 110 | system/alarmgroupallalarms 110 |
| 103 | system/alarmgroupallalarms 103 | 111 | system/alarmgroupallalarms 111 |


| 112 | Low available memory | 120 | HAlarmGroupMemory.m.ID08 |
| :---: | :---: | :---: | :---: |
| 113 | Very low available memory | 121 | HAlarmGroupMemory.m.ID09 |
| 114 | RETAIN memory error | 122 | HAlarmGroupMemory.m.ID10 |
| 115 | Time delayed switch off | 123 | HAlarmGroupMemory.m.ID11 |
| 116 | Low available SD memory | 124 | HAlarmGroupMemory.m.ID12 |
| 117 | Very low available SD memory | 125 | HAlarmGroupMemory.m.ID13 |
| 118 | HAlarmGroupMemory.m.ID06 | 126 | HAlarmGroupMemory.m.ID14 |
| 119 | HAlarmGroupMemory.m.ID07 | 127 | Wireless ID error |


| 128 | Fault CAN master | 136 | IAlarmGroupCANBus.m.ID08 |
| :---: | :---: | :---: | :--- |
| 129 | Fault CAN outputs | 137 | IAlarmGroupCANBus.m.ID09 |
| 130 | Fault CAN FC1 | 138 | IAlarmGroupCANBus.m.ID10 |
| 131 | Fault CAN FC2 | 139 | IAlarmGroupCANBus.m.ID11 |
| 132 | Fault CAN FC3 | 140 | IAlarmGroupCANBus.m.ID12 |
| 133 | Fault CAN FC4 | 141 | IAlarmGroupCANBus.m.ID13 |
| 134 | Fault CAN FC5 | 142 | IAlarmGroupCANBus.m.ID14 |
| 135 | IAlarmGroupCANBus.m.ID07 | 143 | IAlarmGroupCANBus.m.ID15 |

## Notification texts

| 0 | MELDUNG_INIT | Notification after switch on |
| :---: | :--- | :---: |
| 1 | MELDUNG_PAUSE | Pause |
| 2 | MELDUNG_HAND | Manual |
| 3 | MELDUNG_AUS | Off |
| 4 | MELDUNG_BEFUELLEN | Filling |
| 5 | MELDUNG_EXTERN_PAUSE | External pause |
| 8 | MELDUNG_LEER | Minimum weight |
| 9 | MELDUNG_STOERUNG | Fault |


| 10 | MELDUNG_VORLAUF_RUEHRWERK | Agitator startup |
| :---: | :--- | :--- |
| 11 | MELDUNG_VORLAUF_FOERDERSCI | screw 1 startup |
| 12 | MELDUNG_VORLAUF_FOERDERSCI | screw 2 startup |
| 13 | MELDUNG_VORLAUF_FOERDERSCI | screw 3 startup |
| 21 | MELDUNG_VORLAUF_DOSIERSCHN | Metering screw 1 startup |
| 22 | MELDUNG_VORLAUF_DOSIERSCHN | Metering screw 2 startup |
| 23 | MELDUNG_VORLAUF_DOSIERSCHN | Metering screw 3 startup |
| 24 | MELDUNG_VORLAUF_DOSIERSCHN | Metering screw 4 startup |


| 25 | MELDUNG_VORLAUF_DOSIERSCHN | Metering screw 5 startup |
| :---: | :--- | :---: |
| $\mathbf{2 6}$ | MELDUNG_VORLAUF_DOSIERSCHN | Metering screw 6 startup |
| $\mathbf{3 2}$ | MELDUNG_VORLAUF_MISCHER_LA | Mixer slow startup |
| 33 | MELDUNG_VORLAUF_MISCHER_SC | Mixer fast startup |
| 41 | MELDUNG_DOSIERUNG | Dosage |
| 52 | MELDUNG_NACHLAUF_MISCHER_S | Mixer fast run down |
| 53 | MELDUNG_NACHLAUF_MISCHER_L | Mixer slow run down |
| 62 | MELDUNG_NACHLAUF_DOSIERSCH | Metering screw 6 run down |


| 74 | MELDUNG_NACHLAUF_RUEHRWER | Agitator run down |
| :---: | :--- | :---: |
| $\mathbf{8 0}$ | MELDUNG_AUTOMATISCHE_RUECK | Automatic return |
| 81 | MELDUNG_ENTLEERHUB | Emptying stroke |
| 82 | MELDUNG_DUMP_SIGNAL | DUMP Signal |
| 83 | MELDUNG_FREIFAHREN | Retraction |
| 84 | MELDUNG_ANGEFORDERTE_RUEC | Requested return |
| 85 | MELDUNG_WAAGE_BERUHIGUNG | Weighing stabilization |
| $\mathbf{0}$ | 0 | Notification after switch on |


| 63 | MELDUNG_NACHLAUF_DOSIERSCH | Metering screw 5 run down |
| :--- | :--- | :--- |
| 64 | MELDUNG_NACHLAUF_DOSIERSCH | Metering screw 4 run down |
| 65 | MELDUNG_NACHLAUF_DOSIERSCH | Metering screw 3 run down |
| 66 | MELDUNG_NACHLAUF_DOSIERSCH | Metering screw 2 run down |
| 67 | MELDUNG_NACHLAUF_DOSIERSCH | Metering screw 1 run down |
| 71 | MELDUNG_NACHLAUF_FOERDERS | screw 3 run down |
| 72 | MELDUNG_NACHLAUF_FOERDERS | screw 2 run down |
| 73 | MELDUNG_NACHLAUF_FOERDERS | screw 1 run down |

## Icon legend

## Site

## Site

Switches to the page in the red

Currently not available
(U) Here is the overview about

Switches to the feeding page

(b)
Switches to the previous page

Switches to the main menu
(H) Shows the alarm history

Shows the further section of the page

0
Shows the previous section of the page
Additional equipment (for example metering screw) appears on the
\# manual operation page if the system has 1 to 6 additional equipments
Name
Shows the detailed view of the cell, the display or the ADAM module. For example cell 1
Bolean operator is shown, if pause negate is selected in the external equipment
M Flag, pause signal is extended

- Shows if something is selected, not selected

O Shows if something is selected, selected

0
Shows if something is selected, not selected
© Shows if something is selected, selected

©
Here it switches to the cell calibration page
only visible for the admin

S Can indicate the maximum weight value
(D) Send the required address to an arbitrary cell
(Z) Can give individual cells a new 0 value
-0- Set container offset

Shows language file information


Agitator


Mixer motor
(4) Limit switch not activated


Limit switch activated

